



Nationaal Oldtimer Festival

Equipe GTS/Pre'63
Sector analyse - Race 1

28 July 2018
Zandvoort GP - 4307 mtr.

Pos	Nbr	Name / Team name	Sector 1			Sector 2			Sector 3			Theoretical best	Actual best	In
			time	Lap	pos	time	Lap	pos	time	Lap	pos			
1	87	Mark Ashworth	57.833	6	2	33.683	9	1	38.940	6	2	2:10.456	2:10.670	6
2	100	Thorne-Bennett	57.519	7	1	33.980	6	3	38.382	6	1	2:09.881	2:09.893	6
3	146	Bruce Chambers	58.806	13	5	33.976	7	2	39.342	11	4	2:12.124	2:12.608	7
4	98	Nick Matthews	59.005	7	9	34.386	7	5	39.528	6	6	2:12.919	2:13.127	7
5	455	Mark Hope	58.691	14	4	34.325	7	4	39.722	3	10	2:12.738	2:13.194	14
6	102	Winter-Williams	58.889	14	7	34.547	14	6	39.718	5	9	2:13.154	2:13.831	7
7	96	Nigel Brain	58.914	13	8	34.899	6	10	39.635	4	8	2:13.448	2:14.076	4
8	77	John Pearson	58.830	13	6	34.626	14	7	39.253	14	3	2:12.709	2:12.796	14
9	11	Richard Lawson	59.040	8	11	35.112	11	16	39.521	9	5	2:13.673	2:14.194	9
10	223	Garry Townsend	59.173	7	14	34.986	13	13	39.634	3	7	2:13.793	2:14.505	3
11	44	Nick Mountford	59.039	7	10	34.902	8	11	39.975	7	14	2:13.916	2:14.256	7
12	78	David Russell Wilks	59.106	7	12	34.923	7	12	39.942	9	12	2:13.971	2:14.144	7
13	111	Rob Cobden	59.126	6	13	35.065	7	15	40.235	6	16	2:14.426	2:14.449	6
14	5	John Yea											2:15.158	10
15	69	Rob Cull	58.449	7	3	34.682	5	8	39.972	14	13	2:13.103	2:13.282	7
16	73	Mike Lillywhite	59.532	13	17	35.203	10	17	40.469	12	18	2:15.204	2:15.885	13
17	123	Norrie Nichol	59.797	12	18	35.947	14	18	40.155	12	15	2:15.899	2:16.122	12
18	29	Neil Cawthorn	1:01.204	12	20	36.389	11	20	40.574	9	19	2:18.167	2:18.588	11
19	63	Graham Bates	1:00.909	12	19	36.030	10	19	41.057	11	20	2:17.996	2:18.053	11
20	43	Phil Moss	1:01.867	8	21	36.501	13	21	41.283	4	21	2:19.651	2:20.669	8
21	41	Nick Brayshaw	1:04.274	4	22	37.240	4	23	43.010	2	22	2:24.524	2:25.200	4
22	35	Tim Greenhill	59.257	8	15	34.747	8	9	39.829	3	11	2:13.833	2:14.516	8
23	128	Dominic Spicer	1:05.294	4	23	36.973	7	22	43.313	3	23	2:25.580	2:26.358	5
24	83	Ivan Hayward	59.408	3	16	35.031	1	14	40.388	3	17	2:14.827	2:15.247	3