

Malaysia Championship Series Round 1

Thailand Super Series - Race 1
Sector analyse - Race 1



29 March - 1 April 2018
Sepang - 5543 mtr.

Pos	Nbr	Name / Team name	Car	Sector 1			Sector 2			Sector 3			Sector 4			Theoretical best	Actual best	In
				time	Lap	pos	time	Lap	pos	time	Lap	pos	time	Lap	pos			
1	6	Philip Massoud	Chevrolet Camaro	29.158	3	2	30.823	6	3	41.389	6	3	36.587	3	1	2:17.957	2:18.058	3
2	37	Manat Kulapalanont (THA)	Toyota 86	29.669	4	9	30.648	6	2	40.701	6	1	37.675	5	8	2:18.693	2:19.115	6
3	88	Craig Corliss	Ford Mustang	29.357	10	4	30.637	6	1	41.363	3	2	36.701	1	2	2:18.058	2:18.542	4
4	2	Charvanin Bunditkitsada (THA)	Cayman GT4 Clubsport	29.423	3	5	31.311	5	6	41.648	1	5	37.032	8	4	2:19.414	2:20.057	2
5	55	Michael Freeman	Ford Mustang	29.823	4	10	31.025	6	4	42.238	7	7	37.032	5	3	2:20.118	2:20.707	6
6	18	Ian Ross Geekie	Porsche 997 Cup	29.561	6	6	31.084	7	5	41.592	6	4	37.928	9	10	2:20.165	2:20.475	6
7	9	Kmik Kamasuta (THA)	Porsche Cayman GT4	29.577	9	7	31.631	11	10	42.127	3	6	37.824	1	9	2:21.159	2:22.046	9
8	26	Nalin Naeosathon (THA)	Chevrolet Camaro	29.886	5	11	31.490	7	7	42.556	9	11	37.051	9	5	2:20.983	2:21.805	11
9	11	Gregory Bennett	Howe Mustang	29.185	10	3	31.613	8	9	42.431	9	9	37.266	6	7	2:20.495	2:21.669	10
10	8	Sontaya Kunplome (THA)	Porsche Cayman GT4	30.527	11	12	32.513	8	14	43.484	8	13	38.731	8	12	2:25.255	2:25.295	8
11	14	Tosaphol Phamyai (THA)	Porsche Cayman GT4	30.971	6	13	32.092	6	13	44.222	6	15	39.058	9	15	2:26.343	2:26.868	6
12	22	Grant Supaphong (THA)	Dodge Challenger	29.078	6	1	31.640	5	11	42.483	6	10	37.141	5	6	2:20.342	2:20.854	5
13	19	Suttipong Smittachartch (THA)	Toyota 86	31.331	7	14	32.693	7	15	43.728	6	14	39.048	6	14	2:26.800	2:27.223	6
14	46	Pasu Liptapanlop (THA)	Porsche Cayman GT4	29.635	8	8	31.525	8	8	42.254	8	8	38.080	4	11	2:21.494	2:21.619	8
15	7	Weerakarj Dokchan (THA)	Mitsubishi Lancer EVO 9	31.812	2	16	32.089	2	12	43.008	1	12	39.026	1	13	2:25.935	2:27.556	1
16	10	Prateep Tunprasert (THA)	Mitsubishi EvolutionX	31.649	1	15	33.281	1	16				47.594	0	16		2:29.603	1