



Pinksterraces  
Circuit Zandvoort

Equipe GTS  
Sector analyse - Qualifying 1

2 - 4 June 2017  
Zandvoort GP - 4307 mtr.

Pos	Nbr	Name / Team name	Sector 1			Sector 2			Sector 3			Theoretical best	Actual best	In
			time	Lap	pos	time	Lap	pos	time	Lap	pos			
1	80	Simon Cripps	57.245	8	1	32.708	7	1	39.093	8	1	2:09.046	2:09.091	8
2	22	Tom Smith	57.279	6	2	33.146	6	3	39.420	6	3	2:09.845	2:09.845	6
3	69	Rob Cull	57.297	7	3	33.636	7	4	39.235	8	2	2:10.168	2:11.304	7
4	87	Mark Ashworth	58.572	3	5	33.059	6	2	39.818	7	4	2:11.449	2:11.938	6
5	75	Robin Ellis	58.472	8	4	33.926	9	5	39.930	9	5	2:12.328	2:12.917	8
6	77	Pete Foster	58.976	9	7	34.003	9	7	40.125	9	6	2:13.104	2:13.104	9
7	64	Martin Richardson	59.166	7	9	34.144	4	9	40.202	9	7	2:13.512	2:14.002	9
8	94	Andrew Bentley	58.991	9	8	34.174	5	10	40.425	5	10	2:13.590	2:14.060	9
9	90	Rob/Hayleigh Spencer	59.286	9	10	33.984	9	6	40.366	3	8	2:13.636	2:14.109	9
10	19	Jordan/Luke Spencer	58.881	4	6	34.140	2	8	40.475	2	11	2:13.496	2:14.192	3
11	102	Stephen Winter	59.387	5	11	34.705	9	16	40.383	9	9	2:14.475	2:15.258	7
12	73	Mike Lillywhite											2:15.279	6
13	3	Robi Bernberg	59.965	8	13	34.407	9	13	40.768	8	13	2:15.140	2:15.767	9
14	78	David Russell-Wilks	1:00.394	8	16	34.313	6	12	40.632	9	12	2:15.339	2:15.994	8
15	39	Jonathan Smare	59.851	5	12	34.599	8	14	41.174	9	16	2:15.624	2:16.026	9
16	35	Tim Greenhill	1:00.463	4	17	34.200	8	11	41.129	9	15	2:15.792	2:16.116	8
17	11	Richard Lawson	1:00.085	8	14	34.609	5	15	40.946	6	14	2:15.640	2:16.147	5
18	5	John Yea	1:00.624	8	18	35.201	7	18	41.258	7	17	2:17.083	2:18.504	8
19	76	John Pearson	1:01.281	7	19	35.421	8	19	41.417	5	18	2:18.119	2:18.581	7
20	83	Ivan Hayward	1:00.324	4	15	35.047	7	17	41.800	7	19	2:17.171	2:18.591	4
21	33	Paul Kennelly	1:01.855	9	20	35.837	9	21	42.274	9	20	2:19.966	2:19.966	9
22	63	Graham Bates	1:02.224	6	21	35.441	9	20	42.575	8	21	2:20.240	2:20.723	9
23	20	Alex Quattlebaum	1:02.707	6	22	35.839	5	22	42.809	5	22	2:21.355	2:22.708	5
24	43	Phil Moss	1:03.257	5	23	36.288	5	23	42.958	8	23	2:22.503	2:23.043	5